

Sinusoidal Steady-state Analysis

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THE SINUSOIDAL SOURCE

A sinusoidal voltage (current) source produces a voltage (current) that varies sinusoidally with time.

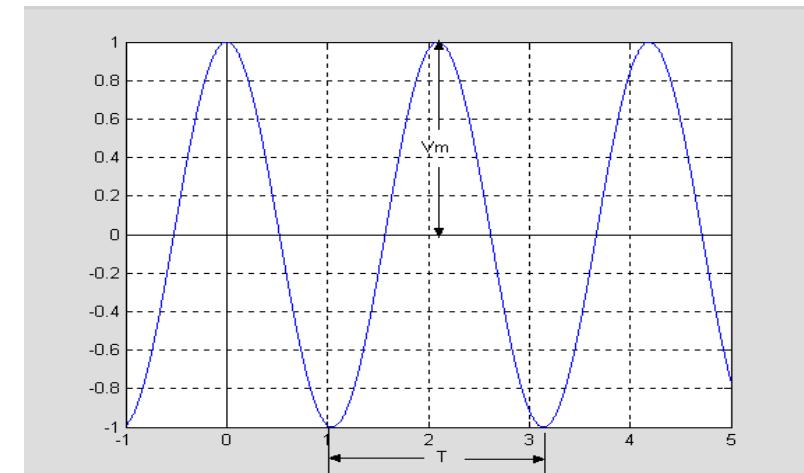
$$v(t) = V_m \cos(\omega t + \theta)$$

V_m is the amplitude,

ω is the frequency in rad/sec.

T: Period of the signal

$$f = \frac{1}{T} \text{ is the frequency in Hz.} \quad \omega = 2\pi f$$

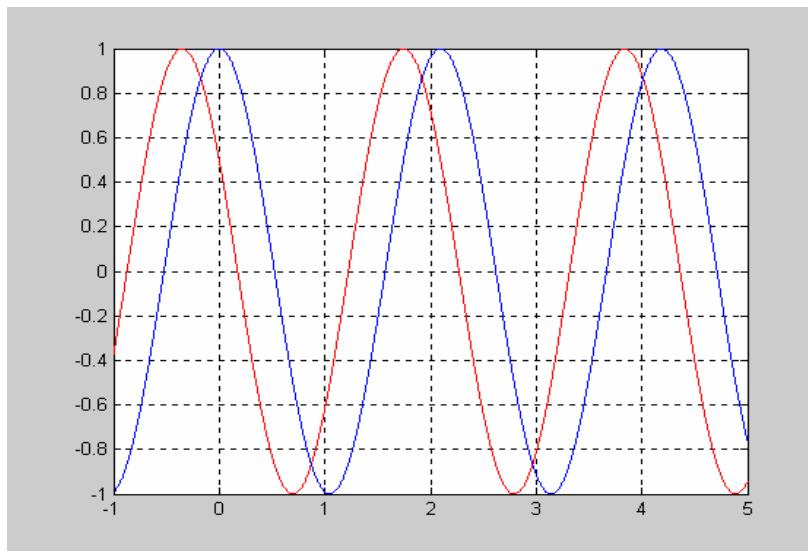


Plot of $\cos(3t)$



PHASE ANGLE

θ in the equation is called the phase angle of the sinusoidal voltage and it determines the value of the function at $t=0$. Changing the phase angle shifts the function along the time axis but has no effect on the amplitude or the angular frequency.



$\cos(3t+30^\circ)$ waveform
leads $\cos 3t$ by 30°

Or

$\cos 3t$ **lags** $\cos(3t+30^\circ)$
by 30°



RMS (root mean square) VALUE

The **rms value** of a periodic function is defined as the square root of the mean value of the squared function.

$$v(t) = V_m \cos(\omega t + \theta) \Rightarrow V_{rms} = \sqrt{\frac{1}{T} \int_{t_0}^{t_0+T} V_m^2 \cos^2(\omega t + \theta) dt} = \frac{V_m}{\sqrt{2}}$$

Example: $v(t) = 300 \cos(120\pi t + 30^\circ)$

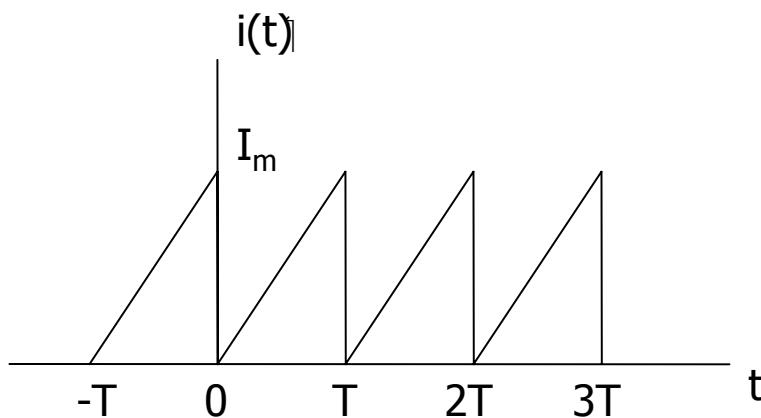
$$\omega = 120\pi \text{ rad/s}, \quad T = \frac{2\pi}{\omega} = \frac{1}{60} = 16.667 \text{ ms}$$

$$f = \frac{1}{T} = 60 \text{ Hz}$$

$$V_{rms} = \frac{300}{\sqrt{2}} = 212.13 V_{rms}$$



EXAMPLE



Find the rms value of $i(t)$

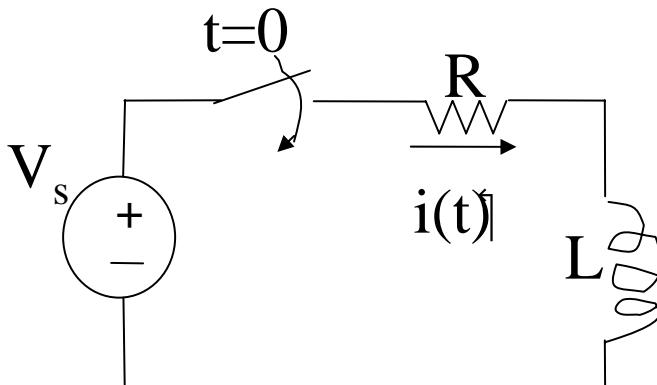
$$i(t) = \frac{I_m}{T}t \quad 0 \leq t \leq T$$

$$I_{rms} = \sqrt{\frac{1}{T} \int_0^T i^2 dt} = \sqrt{\frac{1}{T} \int_0^T \frac{I_m^2}{T^2} t^2 dt} = \frac{I_m}{\sqrt{3}}$$



THE SINUSOIDAL RESPONSE

$$v_s(t) = V_m \cos(\omega t + \theta)$$



Assume that the initial current in the circuit is zero, find $i(t)$ for $t >= 0$.

$$L \frac{di}{dt} + Ri = V_m \cos(\omega t + \theta)$$

The forced response must have the general form

$$i(t) = I_1 \cos \omega t + I_2 \sin \omega t$$

$$L(-I_1 \omega \sin \omega t + I_2 \omega \cos \omega t) + R(I_1 \cos \omega t + I_2 \sin \omega t) = V_m \cos \omega t$$

$$(-LI_1 \omega + RI_2) \sin \omega t + (LI_2 \omega + RI_1 - V_m) \cos \omega t = 0$$



$$-LI_1\omega + RI_2 = 0 \quad \omega LI_2 + RI_1 - V_m = 0$$

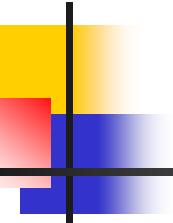
$$I_1 = \frac{RV_m}{R^2 + \omega^2 L^2} \quad I_2 = \frac{\omega LV_m}{R^2 + \omega^2 L^2}$$

$$i(t) = \frac{RV_m}{R^2 + \omega^2 L^2} \cos \omega t + \frac{\omega LV_m}{R^2 + \omega^2 L^2} \sin \omega t$$

A simpler equation may be obtained by expressing $i(t)$ as a single sinusoid with a phase angle

$$i(t) = A \cos(\omega t - \theta) = A \cos \theta \cos \omega t + A \sin \theta \sin \omega t$$

$$A \cos \theta = \frac{RV_m}{R^2 + \omega^2 L^2} \quad A \sin \theta = \frac{\omega LV_m}{R^2 + \omega^2 L^2}$$



$$\tan \theta = \frac{\sin \theta}{\cos \theta} = \frac{\omega L}{R} \Rightarrow \theta = \tan^{-1} \frac{\omega L}{R}$$

$$A^2 \cos^2 \theta + A^2 \sin^2 \theta = \frac{V_m^2}{R^2 + \omega^2 L^2}$$

$$A = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}}$$

$$i(t) = \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos(\omega t - \tan^{-1} \frac{\omega L}{R})$$

Current lags the voltage by $\tan^{-1} \left(\frac{\omega L}{R} \right)$

If $\omega=0$ or $L=0$, the current must be in phase with the voltage.

If $R=0$, current lags the voltage by 90°



THE PHASOR

The phasor is a complex number that carries the amplitude and phase angle information of a sinusoidal function.

$$e^{\pm j\theta} = \cos \theta \pm j \sin \theta$$

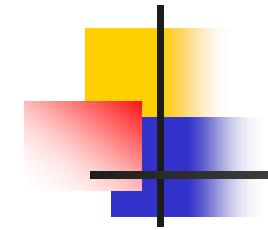
$$\cos \theta = \operatorname{Re}(e^{j\theta}) \quad \text{and} \quad \sin \theta = \operatorname{Im}(e^{j\theta})$$

$$\begin{aligned} v(t) &= V_m \cos(\omega t + \theta) = V_m \operatorname{Re}\{e^{j(\omega t + \theta)}\} \\ &= V_m \operatorname{Re}\{e^{j\omega t} e^{j\theta}\} = \operatorname{Re}\{V_m e^{j\theta} e^{j\omega t}\} \end{aligned}$$

$V_m e^{j\theta}$ Carries the amplitude and phase angle of the given sinusoidal function and is defined as the phasor representation

$\mathbf{V} = V_m e^{j\theta}$ transforms the sinusoidal function from the time domain to the complex number domain, which is also called the frequency domain.




$$\mathbf{V} = V_m \cos \theta + j V_m \sin \theta \quad \text{Rectangular form}$$

$$\mathbf{V} = V_m \angle \theta \quad \text{Angle notation}$$

Inverse Phasor transform: Given $\mathbf{V} = V_m e^{j\theta}$ what is the corresponding time domain function?

$$v(t) = V_m \cos(\omega t + \theta)$$

$$v(t) = v_1(t) + v_2(t) + \dots + v_n(t)$$

Where all the voltages are sinusoidal voltages of the same frequency, then

$$\mathbf{V} = \mathbf{V}_1 + \mathbf{V}_2 + \dots + \mathbf{V}_n$$



Example

$$y_1 = 20 \cos(\omega t - 30^\circ) \quad \text{and} \quad y_2 = 40 \cos(\omega t + 60^\circ)$$

express $y = y_1 + y_2$ as a single sinusoid.

Working in the time domain:

$$\begin{aligned} y &= 20 \cos(\omega t - 30^\circ) + 40 \cos(\omega t + 60^\circ) \\ &= (20 \cos 30^\circ + 40 \cos 60^\circ) \cos \omega t + (20 \sin 30^\circ - 40 \sin 60^\circ) \sin \omega t \\ &= 37.32 \cos \omega t - 24.64 \sin \omega t = \sqrt{37.32^2 + 24.64^2} \cos(\omega t + \tan^{-1} \frac{24.64}{37.32}) \\ &= 44.72 \cos(\omega t + 33.43^\circ) \end{aligned}$$



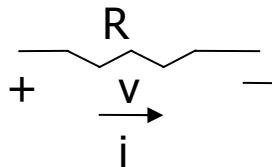
Using phasors

$$\begin{aligned}\mathbf{Y} &= \mathbf{Y}_1 + \mathbf{Y}_2 = 20 \angle -30^\circ + 40 \angle 60^\circ \\ &= (17.32 - j10) + (20 + j34.64) \\ &= 37.32 + j24.64 \\ &= 44.72 \angle 33.43^\circ\end{aligned}$$

$$y = 44.72 \cos(\omega t + 33.43^\circ)$$



The V-I Relationship for a Resistor

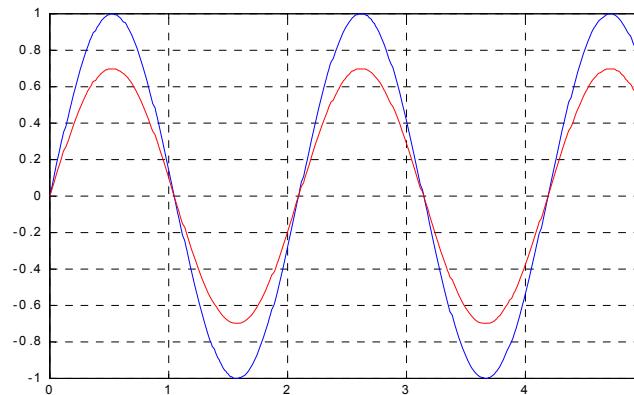


$$i = I_m \cos(\omega t + \theta_i) \Rightarrow v = RI_m \cos(\omega t + \theta_i)$$

$$\mathbf{V} = RI_m e^{j\theta_i} = RI_m \angle \theta_i$$

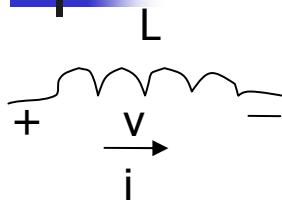
$$\mathbf{I} = I_m \angle \theta_i \Rightarrow \mathbf{V} = R\mathbf{I}$$

The phase angle between voltage and current for a resistor is zero for a resistor. The signals are said to be **in phase**





The V-I Relationship for an Inductor

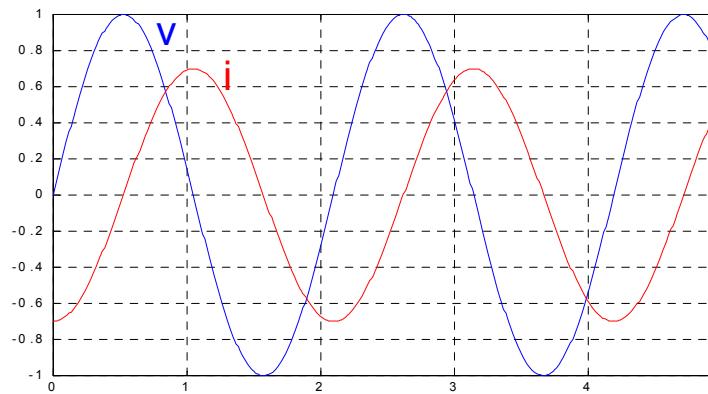


$$i = I_m \cos(\omega t + \theta_i) \Rightarrow v = L \frac{di}{dt} = -\omega L I_m \sin(\omega t + \theta_i)$$

$$v = -\omega L I_m \cos(\omega t + \theta_i - 90^\circ)$$

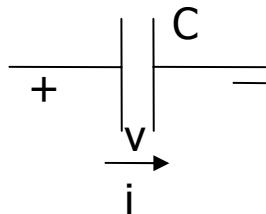
$$\mathbf{V} = -\omega L I_m e^{j(\theta_i - 90^\circ)} = -\omega L I_m e^{j\theta_i} e^{-j90^\circ} = j\omega L I_m e^{j\theta_i} = j\omega L \mathbf{I}$$

The phase difference between voltage and current for an inductor is exactly 90° and voltage leads current or current lags voltage





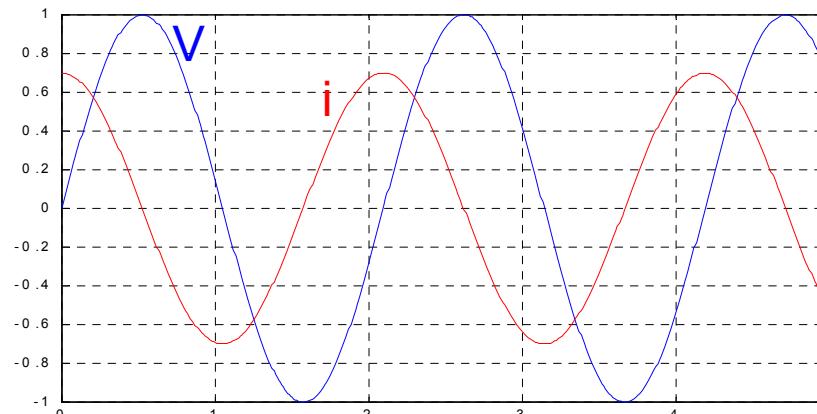
The V-I Relationship for a Capacitor



$$v = V_m \cos(\omega t + \theta_v) \Rightarrow i = C \frac{dv}{dt}$$

$$I = j\omega C V \Rightarrow V = \frac{1}{j\omega C} I$$

Voltage lags the current exactly by 90° for a capacitor.





Impedance and Reactance

Voltage current relationship for a resistor, inductor or capacitor is

$V = ZI$ Where Z represents the **impedance** of the circuit element

Impedance in the frequency domain is the quantity analogous to resistance, inductance, and capacitance in the time domain. The imaginary part of the impedance is called **reactance**

Element	impedance	reactance	
Resistor	R	---	Impedance is measured in Ohms
Inductor	jwL	wL	
Capacitor	$1/jwC$	$1/wC$	



Kirchhoff's Laws in the Frequency Domain

Voltage Law: Sum of the voltages around a closed path in a circuit is zero

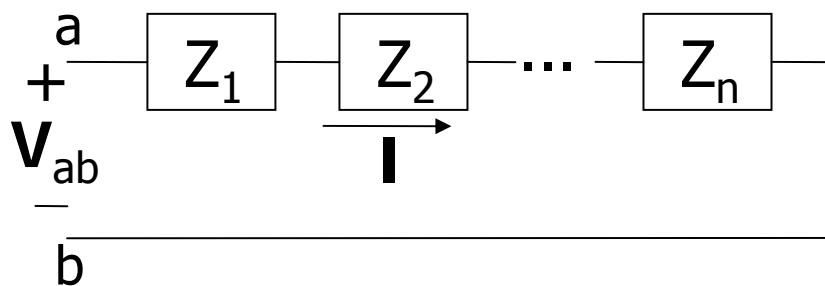
$$v_1 + v_2 + \dots + v_n = 0 \Rightarrow \mathbf{V}_1 + \mathbf{V}_2 + \dots + \mathbf{V}_n = 0$$

Current Law: Sum of the currents entering (leaving) a node is zero

$$i_1 + i_2 + \dots + i_n = 0 \Rightarrow \mathbf{I}_1 + \mathbf{I}_2 + \dots + \mathbf{I}_n = 0$$

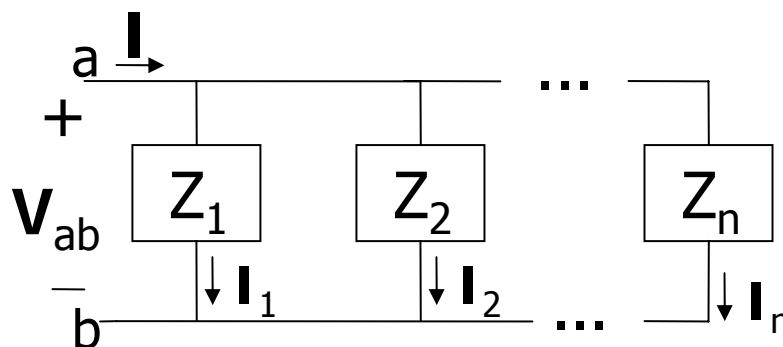


Series and Parallel Impedances

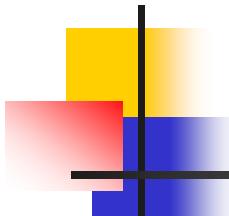


$$\begin{aligned}V_{ab} &= Z_1 I + Z_2 I + \dots + Z_n I \\&= (Z_1 + Z_2 + \dots + Z_n) I\end{aligned}$$

$$Z_{ab} = Z_1 + Z_2 + \dots + Z_n$$



$$\begin{aligned}I &= I_1 + I_2 + \dots + I_n \\ \frac{V_{ab}}{Z_{ab}} &= \frac{V_{ab}}{Z_1} + \frac{V_{ab}}{Z_2} + \dots + \frac{V_{ab}}{Z_n} \\ \frac{1}{Z_{ab}} &= \frac{1}{Z_1} + \frac{1}{Z_2} + \dots + \frac{1}{Z_n}\end{aligned}$$



ADMITTANCE

Admittance is defined as the reciprocal of impedance

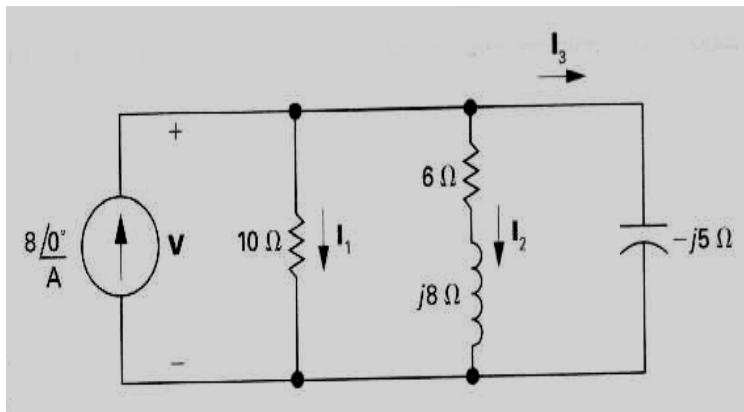
$$Y = \frac{1}{Z} = G + jB$$

G is called conductance and B is called susceptance.

Unit of admittance is mhos



EXAMPLE



Determine the currents
and voltage \mathbf{V} in the circuit.

$$\begin{aligned} \mathbf{I} &= \mathbf{I}_1 + \mathbf{I}_2 + \mathbf{I}_3 = \frac{\mathbf{V}}{10} + \frac{\mathbf{V}}{6+j8} + \frac{\mathbf{V}}{-j5} \\ \mathbf{I} &= 8 \angle 0^\circ \Rightarrow \mathbf{V} = 40 \angle -36.87^\circ = 32 - j24V \\ \mathbf{I}_1 &= \frac{40 \angle -36.87^\circ}{10} = 4 \angle -36.87^\circ A \\ \mathbf{I}_2 &= \frac{40 \angle -36.87^\circ}{6+j8} = 4 \angle -90^\circ = -j4A \\ \mathbf{I}_3 &= \frac{40 \angle -36.87^\circ}{-j5} = 8 \angle 53.13^\circ = 4.8 + j6.4A \end{aligned}$$



$$v = 40 \cos(200000t - 36.87^\circ) V,$$

$$i_1 = 4 \cos(200000t - 36.87^\circ) A,$$

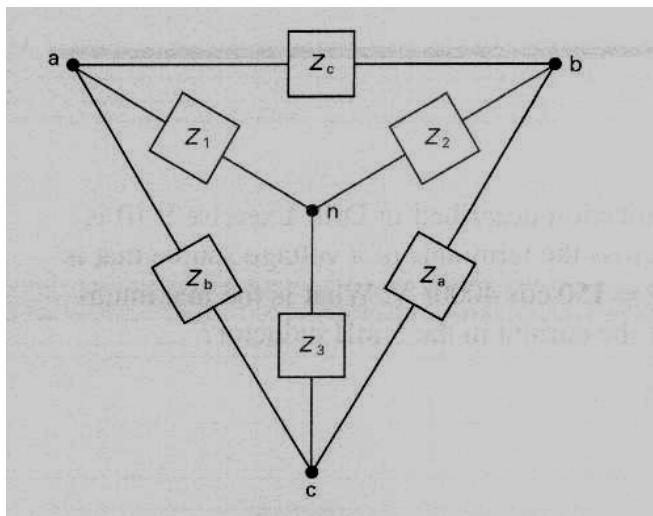
$$i_2 = 4 \cos(200000t - 90^\circ) A,$$

$$i_3 = 8 \cos(200000t + 53.13^\circ) A$$



DELTA-to-Wye Transformations

$\Delta \rightarrow Y$



$$Z_1 = \frac{Z_b Z_c}{Z_a + Z_b + Z_c} \quad Z_2 = \frac{Z_a Z_c}{Z_a + Z_b + Z_c}$$

$$Z_3 = \frac{Z_a Z_b}{Z_a + Z_b + Z_c}$$

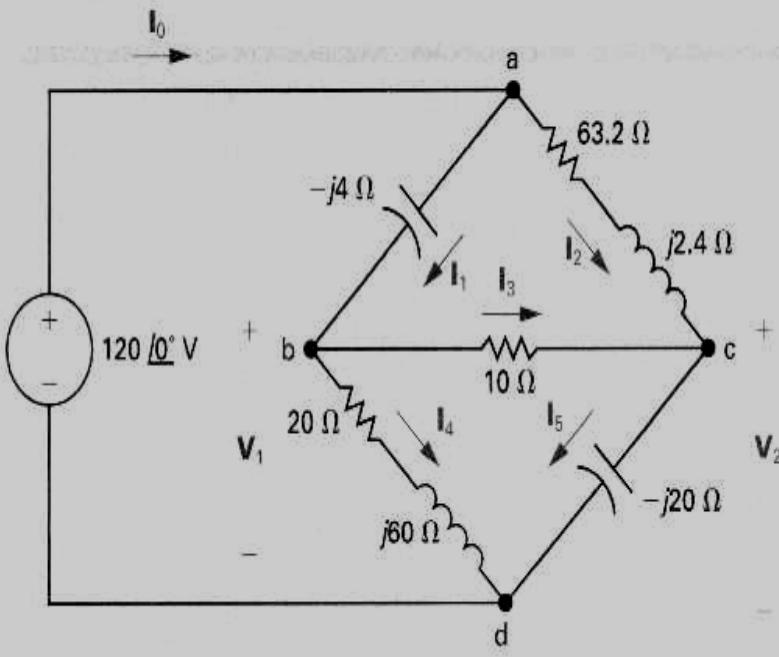
$Y \rightarrow \Delta$

$$Z_a = \frac{Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3}{Z_1} \quad Z_b = \frac{Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3}{Z_2}$$

$$Z_c = \frac{Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3}{Z_3}$$



Example

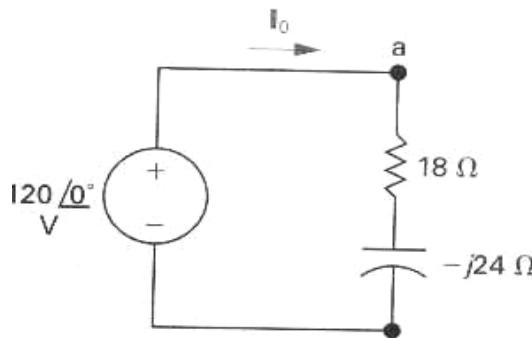
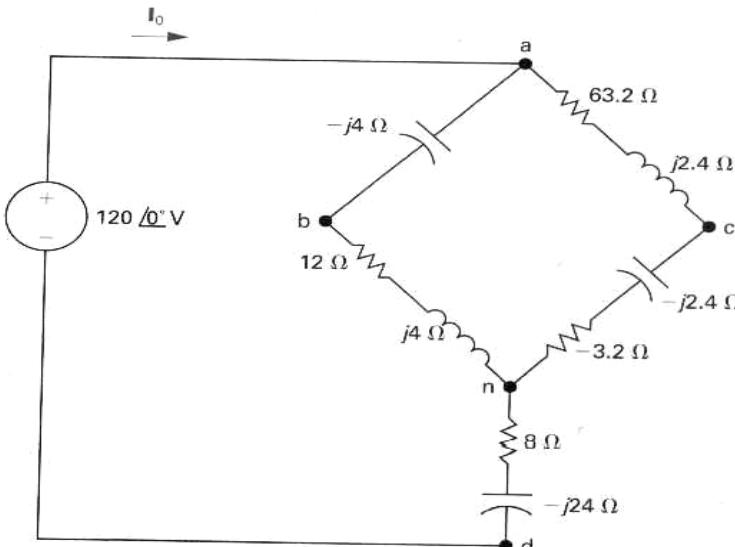
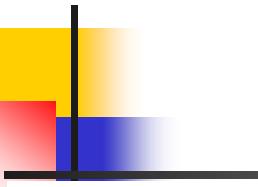


Use a delta-to-wye transformation
to find currents and voltages
in the circuit
Replacing the lower delta by
its Y equivalent:

$$Z_1 = \frac{(20 + j60)10}{30 + j40} = 12 + j4\Omega$$

$$Z_2 = \frac{10(-j20)}{30 + j40} = -3.2 - j2.4\Omega$$

$$Z_3 = \frac{(20 + j60)(-j20)}{30 + j40} = 8 - j2.4\Omega$$



$$Z_{abn} = 12 + j4 - j4 = 12\Omega,$$

$$Z_{acn} = 63.2 + j2.4 - 3.2 - j2.4 = 60\Omega$$

$$Z_{an} = \frac{60 \cdot 12}{72} = 10\Omega$$

$$I_0 = \frac{120 \angle 0^\circ}{18 - j24} = 4 \angle 53.13^\circ = 2.4 + j3.2A$$

$$V_{nd} = (8 - j2.4)I_0 = 96 - j32V$$

$$V_{an} = 120 - 96 + j32 = 24 + j32V$$



$$\mathbf{I}_1 = \frac{24 + j32}{12} = 2 + j\frac{8}{3} A, \quad \mathbf{I}_2 = \frac{24 + j32}{60} = \frac{4}{10} + j\frac{8}{15} A$$

$$\mathbf{V}_1 = 120 - (-j4)\mathbf{I}_1 = \frac{328}{3} + j8V$$

$$\mathbf{V}_2 = 120 - (63.2 + j3.2)\mathbf{I}_2 = 96 - j\frac{104}{3}V$$

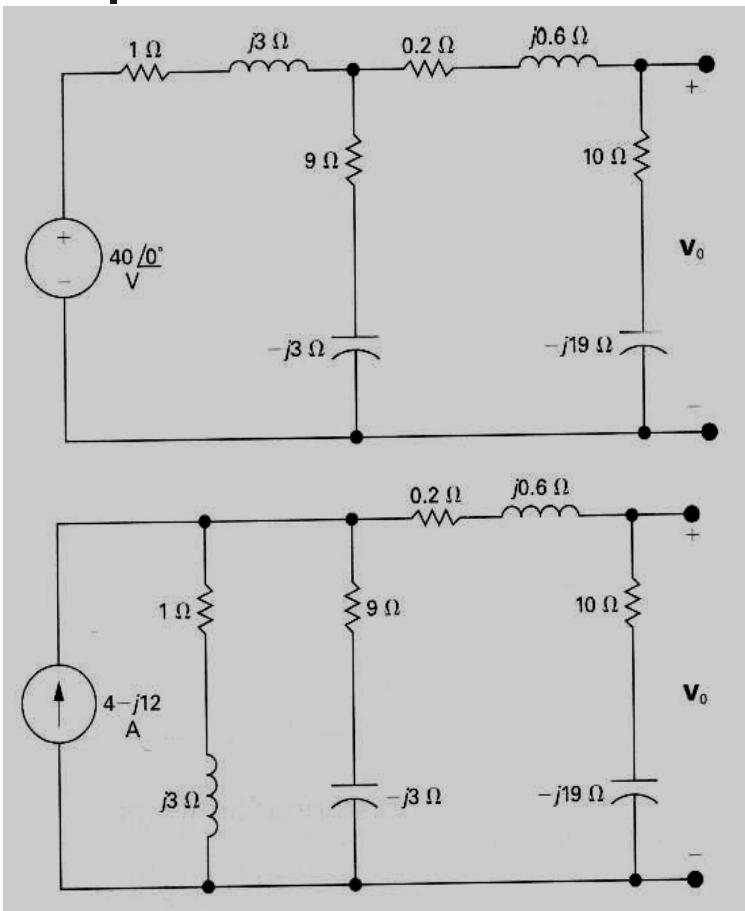
$$\mathbf{I}_3 = \frac{\mathbf{V}_1 - \mathbf{V}_2}{10} = \frac{4}{3} + j\frac{12.8}{3} A$$

$$\mathbf{I}_4 = \frac{\mathbf{V}_1}{20 + j60} = \frac{2}{3} - j1.6A$$

$$\mathbf{I}_5 = \frac{\mathbf{V}_2}{-j20} = \frac{26}{15} + j4.8A$$



SOURCE TRANSFORMATIONS



Circuit Analysis II

Find V_0 using successive
source transformations

$$I_0 = \frac{40}{1+j3} = 4 - j12A$$

$$Z = \frac{(1+j3)(9-j3)}{10} = 1.8 + j2.4\Omega$$

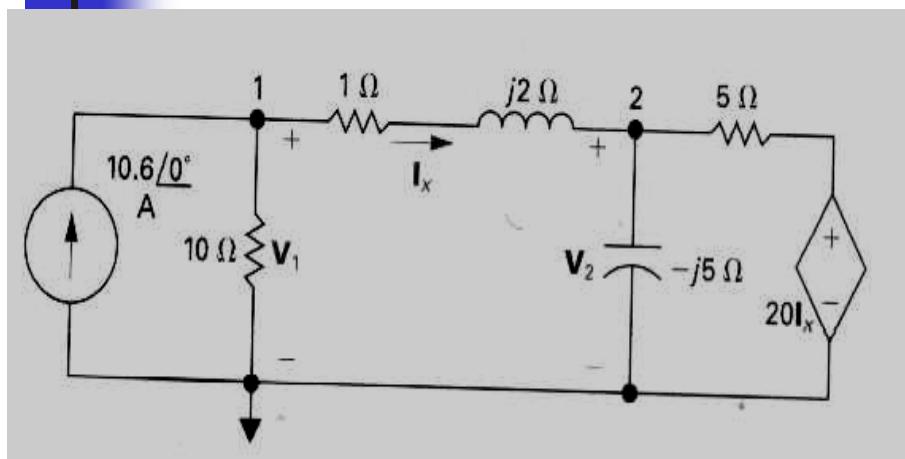
$$V = (4 - j12)(1.8 + j2.4) = 36 - j12V$$

$$I_0 = \frac{36 - j12}{12 - j16} = 1.56 + j1.08A$$

$$V_0 = (1.56 + j0.8)(10 - j19) = 36.12 - j18.84V$$



THE NODE-VOLTAGE METHOD



Use the node-voltage method to find \mathbf{V}_1 and \mathbf{V}_2 in the circuit.

$$-10.6 + \frac{\mathbf{V}_1}{10} + \frac{\mathbf{V}_1 - \mathbf{V}_2}{1 + j2} = 0$$

$$\frac{\mathbf{V}_2 - \mathbf{V}_1}{1 + j2} + \frac{\mathbf{V}_2}{-j5} + \frac{\mathbf{V}_2 - 20\mathbf{I}_x}{5} = 0$$

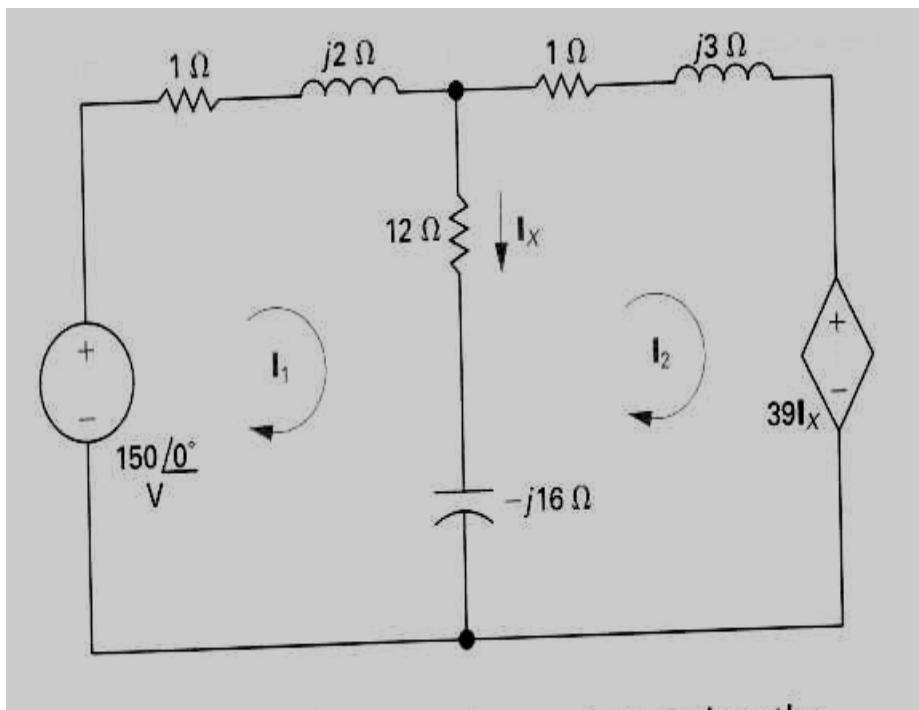
$$\mathbf{I}_x = \frac{\mathbf{V}_1 - \mathbf{V}_2}{1 + j2}$$

$$\mathbf{V}_1 = 68.4 - j16.8V$$

$$\mathbf{V}_2 = 68 - j26V$$



THE MESH-CURRENT METHOD



Use the mesh-current method
to find \mathbf{I}_1 and \mathbf{I}_2

$$150 = (1 + j2)\mathbf{I}_1 + (12 - j16)(\mathbf{I}_1 - \mathbf{I}_2)$$

$$0 = (12 - j16)(\mathbf{I}_2 - \mathbf{I}_1) + (1 + j3)\mathbf{I}_2 + 39\mathbf{I}_x$$

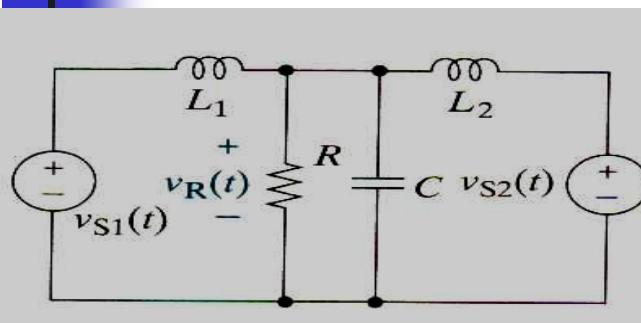
$$\mathbf{I}_x = \mathbf{I}_1 - \mathbf{I}_2$$

$$\mathbf{I}_1 = -26 - j52A$$

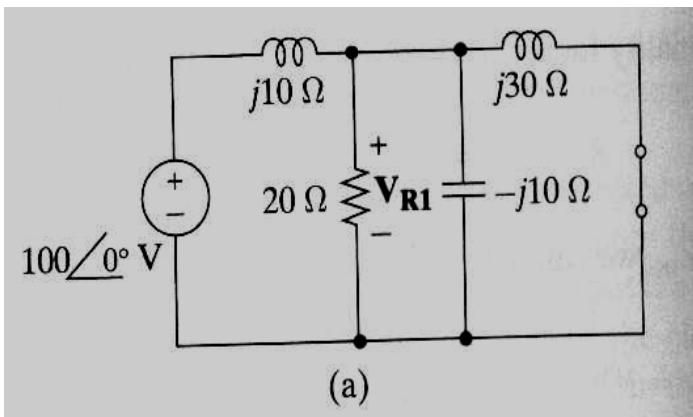
$$\mathbf{I}_2 = -24 - j58A$$



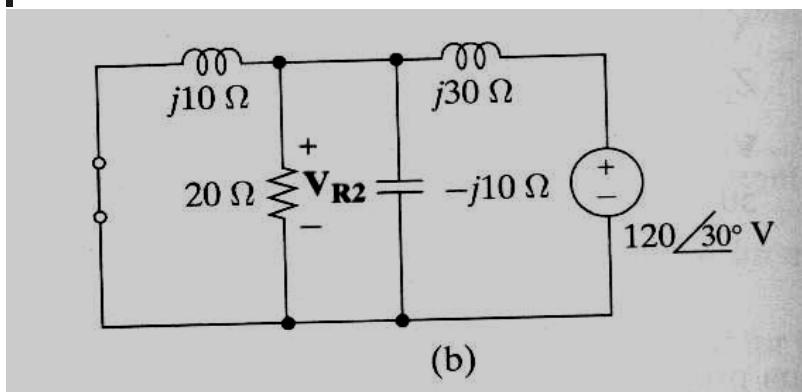
SUPERPOSITION



Use superposition to determine $v_R(t)$ for $R=20\Omega$, $L_1=2\text{ mH}$, $L_2=6\text{ mH}$, $C=20\mu\text{F}$, $v_{S1}(t)=100 \cos 5000t \text{ V}$, and $v_{S2}(t)=120 \cos(5000t+30^\circ) \text{ V}$.



$$\begin{aligned} Z_{eq1} &= \frac{1}{\frac{1}{20} + \frac{1}{-j10} + \frac{1}{j30}} = 7.2 - j9.6\Omega \\ \mathbf{V}_{R1} &= \frac{Z_{eq1}}{j10 + Z_{eq1}} 100 \angle 0^\circ \\ &= 92.3 - j138 = 166 \angle -56.3^\circ \text{ V} \end{aligned}$$



$$Z_{eq2} = \frac{1}{\frac{1}{20} + \frac{1}{-j10} + \frac{1}{j10}} = 20 - j0\Omega$$

$$\mathbf{V}_{R2} = \frac{Z_{eq2}}{j30 + Z_{eq2}} 120 \angle 30^\circ$$

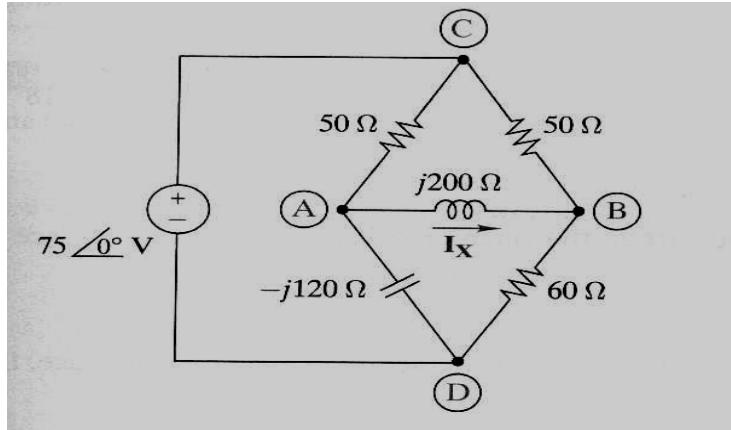
$$= 59.7 - j29.5 = 66.6 \angle -26.3^\circ V$$

$$\mathbf{V}_R = \mathbf{V}_{R1} + \mathbf{V}_{R2} = 152 - j167 = 226 \angle -47.8^\circ V$$

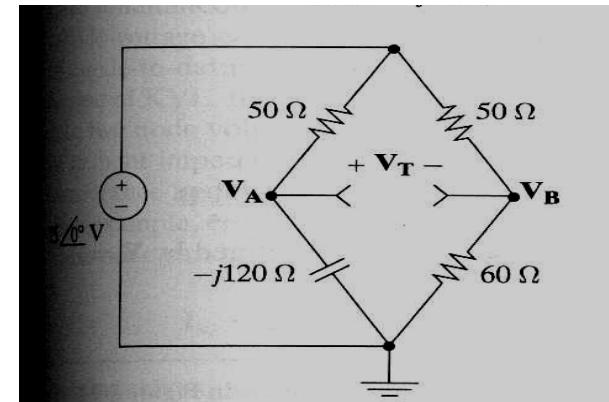
$$\begin{aligned} v_R(t) &= 166 \cos(5000t - 56.3^\circ) + 66.6 \cos(5000t - 26.3^\circ) \\ &= 226 \cos(5000t - 47.8^\circ) V \end{aligned}$$



THEVENIN EQUIVALENT



Use Thevenin's theorem to find the current I_x in the circuit.



$$V_T = V_A - V_B = \frac{-j120}{50 - j120} 75\angle 0^\circ - \frac{60}{60 + 50} 75\angle 0^\circ$$
$$= 23 - j26.6V$$

$$Z_{Th} = \frac{1}{\frac{1}{50} + \frac{1}{-j120}} + \frac{1}{\frac{1}{50} + \frac{1}{60}} = 69.9 - j17.8\Omega$$

$$I_x = \frac{V_T}{Z_{Th} + j200} = \frac{23 - j26.6}{69.9 + j182.2} = 0.18\angle -118^\circ A$$